The Volume of Relaxed Boolean-Quadric and Cut Polytopes

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Abstract. For $n \geq 2$, the boolean quadric polytope $\mathcal{P}_n$ is the convex hull in $d := \binom{n+1}{2}$ dimensions of the binary solutions of $x_ix_j = y_{ij}$, for all $i < j$ in $N := \{1, 2, ..., n\}$. The polytope is naturally modeled by a somewhat larger polytope; namely, $\mathcal{Q}_n$ the solution set of $y_{ij} \leq x_i$, $y_{ij} \leq x_j$, $x_i + x_j \leq 1 + y_{ij}$, $y_{ij} \geq 0$, for all $i, j$ in $N$. In a first step toward seeing how well $\mathcal{Q}_n$ approximates $\mathcal{P}_n$, we establish that the $d$-dimensional volume of $\mathcal{Q}_n$ is $2^{2n-d_n!}/(2n)!$. Using a well-known connection between $\mathcal{P}_n$ and the “cut polytope” of a complete graph on $n + 1$ vertices, we also establish the volume of a relaxation of this cut polytope.

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1. Introduction. A natural approach to the unconstrained, quadratic-objective, binary program in \( n \) \( (\geq 2) \) variables

\[
\max \left\{ \sum_{i \in N} c_i x_i + \sum_{i < j \in N} d_{ij} x_i x_j : x_i \in \{0, 1\} \ \forall \ i \in N \right\},
\]

where \( N := \{1, 2, ..., n\} \), is to model the problem as a linearly constrained, linear-objective, binary program, through the use of \( \binom{n}{2} \) auxiliary binary variables \( y_{ij} \) which model the quadratic terms \( x_i x_j \). We obtain the equivalent program

\[
\max \sum_{i \in N} c_i x_i + \sum_{i < j \in N} d_{ij} y_{ij},
\]

subject to \( y_{ij} \leq x_i \ \forall \ i < j \in N \),
(3)
\( y_{ij} \leq x_j \ \forall \ i < j \in N \),
(4)
\( y_{ij} \geq 0 \ \forall \ i < j \in N \),
(5)
\( x_i + x_j \leq 1 + y_{ij} \ \forall \ i < j \in N \),
(6)
\( x_i \in \{0, 1\} \ \forall \ i \in N \),
(7)
\( y_{ij} \in \{0, 1\} \ \forall \ i < j \in N \). (8)

The boolean quadric polytope \( P_n \) is the convex hull (in real \( d := \binom{n+1}{2} \) space) of the set of solutions of (3-8). As the problem of solving (2-8) is NP-Hard, it is natural to consider branch-and-cut methods based on (2-6). The relaxed feasible region (3-6) is denoted by \( Q_n \). Padberg (1989) has made a detailed study of \( P_n \) and \( Q_n \) (also see Deza, Laurent and Poljak (1993), and PadTowsky (1991)).

It is natural to consider how good of an approximation \( Q_n \) is to \( P_n \). The Chvátal-Gomory rank (see Schrijver (1986) and Chvátal, Cook and Hartman (1989)) of \( P_n \) with respect to \( Q_n \) increases with \( n \), so in a certain combinatorial sense, \( Q_n \) is a poor approximation of \( P_n \). In a different combinatorial sense \( Q_n \) is quite close to \( P_n \); that is, the 1-skeleton of \( P_n \) is a subset of the 1-skeleton of \( Q_n \) (the so-called Trubin Property) (see Padberg). Another method has been proposed to study the closeness of pairs of nested polytopes, based on the volumes of the polytopes. Lee and Morris (1994) have suggested the distance function

\[
\rho_d(Q_n, P_n) := \left( \frac{\text{vol}_d(Q_n)}{\text{vol}_d(B^d)} \right)^{1/d} - \left( \frac{\text{vol}_d(P_n)}{\text{vol}_d(B^d)} \right)^{1/d},
\]

where \( B^d \) is the \( d \)-dimensional Euclidean ball, and \( \text{vol}_d \) denotes \( d \)-dimensional Lebesgue measure. For polytope pairs contained in \([0, 1]^d\), \( \rho_d \) is at most \( O(\sqrt{d}) \). In some interesting
cases of sets of polytope pairs, \( \rho_d \) may increase more slowly than this upper bound, in other situations the bound is sharp (see Lee and Morris). In Section 2, as a step toward determining the asymptotic behavior of \( \rho_d(Q_n, P_n) \), we calculate \( \text{vol}_d(\mathcal{Q}_n) \).

There is a well-known connection between \( P_n \) and the “cut polytope” of a complete graph on \( n + 1 \) vertices. In Section 3, we determine the volume of a natural relaxation of this cut polytope.

2. The Volume of a Relaxed Boolean-Quadric Polytope. Let \( \mathcal{Q}'_n := 2\mathcal{Q}_n \), that is, the polytope \( \mathcal{Q}_n \) magnified by a factor of 2. Clearly, \( \text{vol}_d(\mathcal{Q}'_n) = 2^d\text{vol}_d(\mathcal{Q}_n) \). Padberg demonstrated that \( \mathcal{Q}'_n \) is a lattice polytope (i.e., its extreme points are lattice points). For simplicity, we work with \( \mathcal{Q}'_n \), which is defined by the inequalities

\[
\begin{align*}
y_{ij} &\leq x_i \quad \forall i < j \in N, \\
y_{ij} &\leq x_j \quad \forall i < j \in N, \\
y_{ij} &\geq 0 \quad \forall i < j \in N, \\
x_i + x_j &\leq 2 + y_{ij} \quad \forall i < j \in N.
\end{align*}
\]

Our first step in calculating \( \text{vol}_d(\mathcal{Q}'_n) \) is to reduce the problem to that of calculating the volume of a subset of \( \mathcal{Q}'_n \). Points in Euclidean \( d \)-space will be denoted by \((x, y) = (x_1, x_2, \ldots, x_n, y_1, y_2, \ldots, y_n, 1)\). For \( a \in \{0,1\}^n \), let

\[ C_a := \{(x, y) \in \mathcal{Q}'_n : a \leq x \leq a + 1\}, \]

where \( 1 \) is the \( n \)-vector \((1, 1, \ldots, 1)\). Clearly, \( \mathcal{Q}'_n \) is the union of all such polytopes \( C_a \). Furthermore, \( \text{vol}_d(C_a \cap C_b) = 0 \) for \( a \neq b \), so \( \text{vol}_d(\mathcal{Q}'_n) = \sum_a \text{vol}_d(C_a) \).

Proposition 1. \( \text{vol}_d(C_a) = \text{vol}_d(C_0), \) for all \( a \in \{0,1\}^n \).

Proof: It suffices to demonstrate that if binary \( n \)-vectors \( a \) and \( b \) differ in precisely one coordinate, then \( \text{vol}_d(C_a) = \text{vol}_d(C_b) \). Suppose, without loss of generality, that \( a_j = b_j \) for \( j \neq i \), \( a_i = 0 \), and \( b_i = 1 \). We define a map \( \Phi_i : C_a \mapsto C_b \) as follows: \( \Phi_i \) is a composition of coordinate maps \( \{\phi_i, \phi_j, \phi_{ki}, \phi_{ij}, \phi_{kj} : 1 \leq k < i < j \leq n\} \), where \( \phi_i(x_i) := 2 - x_i \), \( \phi_j(x_j) := x_j \) for \( j \neq i \), \( \phi_{kj}(y_{kj}) := y_{kj} \), \( \phi_{ij}(y_{ij}) := x_j - y_{ij} \), and \( \phi_{ki}(y_{ki}) := x_k - y_{ki} \). To see that the range of \( \Phi_i \) is contained in \( C_b \), we only need to consider \( \phi_{ij} \); the analysis for \( \phi_{ki} \) is similar. Clearly,

\[ \phi_{ij}(y_{ij}) = x_j - y_{ij} \leq x_j = \phi_j(x_j), \]

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and
\[ \phi_{ij}(y_{ij}) = x_j - y_{ij} \leq x_j - x_i - x_j + 2 = 2 - x_i = \phi_i(x_i). \]

Also,
\[ \phi_i(x_i) + \phi_j(x_j) = 2 - x_i + x_j \leq 2 - y_{ij} + x_j = 2 + \phi_{ij}(y_{ij}). \]

Thus, we have shown that \( \Phi_i \) is, indeed, a map from \( C_a \) into \( C_b \).\(^1\) It is trivial to check that \( \Phi_i \) is an involution. Consequently, \( \Phi_i \) is bijective and unimodular, and thus measure preserving, so \( \text{vol}_d(C_a) = \text{vol}_d(C_b) \). Now, given an arbitrary binary \( n \)-vector \( a \), the composition of the maps in \( \{ \Phi_i : a_i = 1 \} \) gives a measure preserving bijection from \( C_0 \) to \( C_a \), so \( \text{vol}_d(C_a) = \text{vol}_d(C_0) \).

**Corollary 2.** \( \text{vol}_d(Q'_n) = 2^n \text{vol}_d(C_0) \). \( \blacksquare \)

Let \((S_n, \prec)\) denote the poset (partially ordered set) on \( S_n := \{ x_i : 1 \leq i \leq n \} \cup \{ y_{ij} : 1 \leq i < j \leq n \} \) having \( y_{ij} \prec x_i \) and \( y_{ij} \prec x_j \). Let \( e(S_n, \prec) \) denote the number of (linear) extensions of \((S_n, \prec)\), i.e., the number of order-preserving bijections from \( S_n \) to \( D := \{ 1, 2, ..., d \} \), where the order on \( D \) is the usual one.

**Proposition 3.** \( \text{vol}_d(C_0) = e(S_n, \prec)/d! \)

**Proof:** By definition,
\[ C_0 = \{ (x, y) \in Q'_n : 0 \leq x_i \leq 1 \ (1 \leq i \leq n) \} \).

It follows that \( C_0 \) is defined by the inequalities \((9 - 11)\) and
\[ x_i \leq 1, \ 1 \leq i \leq n, \]
with \((12)\) rendered vacuous. \( C_0 \) is the order polytope (see Stanley (1986)) of the poset \((S_n, \prec)\). The result follows by Corollary 4.2 of Stanley. \( \blacksquare \)

**Theorem 4.** \( e(S_n, \prec) = n!d!2^n/(2n)! \).

**Proof:** We regard extensions of \((S_n, \prec)\) as permutations of the set \( S_n \). That is, given a bijection \( \pi : S_n \rightarrow D \), we represent \( \pi \) by the permutation \( \pi^{-1}(d)\pi^{-1}(d-1)\cdots\pi^{-1}(1) \). Define an ordered extension of \((S_n, \prec)\) to be an extension of \((S_n, \prec)\) such that \( x_i \) appears to the left of \( x_k \), for \( 1 \leq i < k \leq n \). That is, we regard an ordered extension of \((S_n, \prec)\) as

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\(^1\) The map \( \Phi_i \) is called a “switching” and is a standard tool in the analysis of the “cut polytope” (see Deza and Laurent (1992) and Pitowsky (1991)).
a permutation of \( S_n \) in which \( x_i \) appears to the left of \( x_k \), and \( y_{ik} \) appears to the right of both \( x_i \) and \( x_k \), for \( 1 \leq i < k \leq n \). Clearly the number of extensions equals \( n! \) times the number of ordered extensions.

Next, we proceed to count the number of ordered extensions of \((S_n, \prec)\). Suppose that \( \{y_{il} : k + 1 \leq l \leq n\} \) have already been positioned, for some fixed \( i < k + 1 \). We see, now, how to place \( \{y_{lk} : 1 \leq l \leq k - 1\} \). The element \( y_{lk} \) should be placed to the right of \( x_k \). As there are already \( f_k \equiv n - k + 1 + \binom{n}{2} - \binom{k}{2} \) elements of \( S_n \) placed after \( x_k \), there are \( f_k \) possible positions for \( y_{lk} \). Then, there are \( f_k + 1 \) possible positions for \( y_{2k} \), up through \( f_k + k - 1 \) possible positions for \( y_{k-1,k} \). In total, the number of ordered extensions is equal to

\[
\prod_{k=2}^{n} \prod_{i=0}^{k-2} (f_k + i) = \prod_{k=2}^{n} \frac{(f_k + k - 2)!}{(f_k - 1)!} = \prod_{k=2}^{n} \frac{\left( \frac{(n+1)!}{2} - \frac{k!}{2} \right)!}{\left( \frac{(n+1)!}{2} - \frac{(k+1)!}{2} \right)!} = \frac{2^n \cdot d!}{(2n)!}
\]

Hence, we get that \( e(S_n, \prec) = \frac{n! \cdot d! \cdot 2^n}{(2n)!} \).

Corollary 2, Proposition 3, and Theorem 4 now yield

**Theorem 5.** \( \text{vol}_d(Q_n) = 2^{2n-d}n!/(2n)! \).

We note that by Stirling’s formula, \( \text{vol}_d(Q_n') = 2^{-1/2}(e/n)^n(1 + o(1)) \). Hence, for example, if it could be shown that \( \text{vol}_d(2P_n) = 2^{-1/2}(e/n)^d(1 + o(1)) \), then we could conclude that \( \rho_d(Q_n, P_n) \) behaves like \( \sqrt{d} \).

3. The Volume of a Relaxed Cut-Polytope of a Complete Graph. Let \( G \) be a simple undirected graph with vertex set \( V(G) := \{0,1,2,...,n\} = N \cup \{0\} \) and edge set \( E(G) \). A cut of \( G \) is any set of edges that crosses a nontrivial partition of \( V(G) \); that is, \( F \subset E(G) \) is a cut if \( F \) is the set of edges with exactly one endpoint in some nonempty proper subset \( W \) of \( V(G) \). Associated with every cut of \( G \) is its incidence vector \( z \in \{0,1\}^{E(G)} \). Let the cut polytope of \( G \) be the convex hull of the incidence vectors of cuts of \( G \). For the complete graph \( K_{n+1} \), we denote the cut polytope by \( C_{n+1} \). We immediately notice that \( P_n \) and \( C_{n+1} \) both have dimension \( d = \binom{n+1}{2} \). As has been observed by many authors (see Deza and Laurent), there is a linear bijective transformation \( \tau \) from \( P_n \) to
\( C_{n+1}; \text{namely,} \)

\[
x_i := z_{0i} \quad \forall \ i \in N,
\]

\[
y_{ij} := \frac{1}{2}(z_{0i} + z_{0j} - z_{ij}) \quad \forall \ i < j \in N.
\]

We may apply this same transformation to the relaxed Boolean-quadric polytope and define \( D_{n+1} := \tau(Q_n) \), a natural relaxation of \( C_{n+1} \). The polytope \( D_{n+1} \) is the solution set of

\[
\begin{align*}
z_{0i} - z_{0j} - z_{ij} & \leq 0 \quad \forall \ i < j \in N, \\
z_{0i} + z_{0j} - z_{ij} & \leq 0 \quad \forall \ i < j \in N, \\
z_{0i} - z_{0j} + z_{ij} & \leq 0 \quad \forall \ i < j \in N, \\
z_{0i} + z_{0j} + z_{ij} & \leq 2 \quad \forall \ i < j \in N.
\end{align*}
\]

Let \( x := \{x_1, x_2, \ldots, x_n\}^T, \ z^0 := (z_{01}, z_{02}, \ldots, z_{0n})^T, \ z := (z_N^0) \), and define \( y \) and \( z^N \) so that \( y_{ij} \) occupies the same position in \( y \) as \( z_{ij} \) does in \( z^N \), \( i < j \in N \). In matrix terms, we can view the transformation \( \tau \) as

\[
\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} I & 0 \\ \frac{1}{2} A^T & -\frac{1}{2} I \end{pmatrix} \begin{pmatrix} z^0 \\ z^N \end{pmatrix},
\]

where \( A \) is a vertex-edge incidence matrix of \( K_n \) on vertex set \( N \). The absolute value of the determinant of the transformation matrix is \( 2^{n-d} \), so we can conclude the following result.

**Theorem 6.** \( \text{vol}_d(D_{n+1}) = 2^n n!/(2n)! \). □

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**References**


